

The Blow-up of Solutions of Parabolic Equation System with Critical Exponential Nonlinearity

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Abstract: We consider the Cauchy problem:

$$\begin{cases} u_t - \Delta u + \lambda_1 u = \mu_1 u (e^{u^2} - 1) + \beta v (e^{uv} - 1) & \text{in } \Omega \times T, \\ v_t - \Delta v + \lambda_2 v = \mu_2 v (e^{v^2} - 1) + \beta u (e^{uv} - 1) & \text{in } \Omega \times T, \\ u(x, 0) = u_0(x) & \text{in } \Omega, \\ v(x, 0) = v_0(x) & \text{in } \Omega, \end{cases}$$

where Ω is a bounded smooth domain, $\lambda_1, \lambda_2 > -\Lambda_1$ (the first eigenvalue of $(-\Delta, H_0^1(\Omega))$), $\mu_1, \mu_2 > 0$ and β is large. The nonlinear term has a critical growth at infinity in the energy space $H^1(\Omega)$ in view of the Moser-Trudinger embedding. Our goal is to investigate from the initial data $(u_0, v_0) \in H_0^1(\Omega) \times H_0^1(\Omega) \setminus \{(0, 0)\}$ whether the solution blows up in finite time. We prove that for initial data with energies below or equal to the ground state level, the dichotomy between finite time blow-up can be determined by means of a potential well argument.

Keywords: Moser-Trudinger inequality; Critical growth; Parabolic system

1 Introduction

We consider the Cauchy problem for a two-space dimensional parabolic equation system with exponential-type nonlinearity; more precisely, we focus the attention on the following model problem:

$$\begin{cases} u_t - \Delta u + \lambda_1 u = \mu_1 u (e^{u^2} - 1) + \beta v (e^{uv} - 1) & \text{in } \Omega \times T, \\ v_t - \Delta v + \lambda_2 v = \mu_2 v (e^{v^2} - 1) + \beta u (e^{uv} - 1) & \text{in } \Omega \times T, \\ u(x, 0) = u_0(x) & \text{in } \Omega, \\ v(x, 0) = v_0(x) & \text{in } \Omega, \end{cases} \quad (1)$$

where $\Omega \subset \mathbb{R}^2$ is a bounded domain with sufficiently smooth boundary, $\lambda_1, \lambda_2 > -\Lambda_1$ with $\Lambda_1 = \Lambda_1(\Omega)$ the first eigenvalue of $(-\Delta, H_0^1(\Omega))$, and we consider initial data in the energy space $H_0^1(\Omega)$, i.e.,

$$(u_0, v_0) \in X.$$

where $X := H_0^1(\Omega) \times H_0^1(\Omega)$

In this framework, energy refers to the functional associated with the stationary problem:

$$I(u, v) = \frac{1}{2} \int_{\Omega} (\lambda_1 u^2 + |\nabla u|^2 + \lambda_2 v^2 + |\nabla v|^2) dx - \int_{\Omega} H(u, v) dx$$

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where

$$H(u, v) = \frac{\mu_1}{2} G(u, u) + \beta G(u, v) + \frac{\mu_2}{2} G(v, v) \quad \text{and} \quad G(u, v) = e^{uv} - 1 - uv.$$

$$\|(u, v)\|_{H^1} := \left(\|\nabla u\|_{L^2}^2 + \lambda_1 \|u\|_{L^2}^2 + \|\nabla v\|_{L^2}^2 + \lambda_1 \|v\|_{L^2}^2 \right)^{\frac{1}{2}}$$

and

$$\|(u, v)\|_{L^2}^2 := \left(\|u\|_{L^2}^2 + \|v\|_{L^2}^2 \right) \quad \text{and} \quad \|\nabla(u, v)\|_{L^2}^2 = \left(\|\nabla u\|_{L^2}^2 + \|\nabla v\|_{L^2}^2 \right).$$

The above functional is well defined in $H^1(\Omega)$, and the nonlinear term $\mu_1 u(e^{u^2} - 1)$ and $\mu_2 v(e^{v^2} - 1)$ that we are considering have critical growth in the energy space in view of the Trudinger-Moser embedding [2].

We define the maximal existence time T_* of the solution

$$T_* := \sup \{ T > 0 : \text{the problem (1.1) admits a solution } (u, v) \in C([0, T]; H^1(\Omega) \times H^1(\Omega)) \} \in (0, +\infty].$$

Polynomial case. Let $\Omega \subset \mathbb{R}^N$, $N \geq 3$, be a smooth bounded domain, and let us consider

$$\begin{cases} \partial_t w = \Delta w + |w|^{p-1} w & \text{in } \Omega \times (0, T), \\ w(x, t) = 0 & \text{in } \partial\Omega \times (0, T), \\ w(x, 0) = w_0(x) & \text{in } \Omega, \end{cases} \quad (2)$$

with $1 < p \leq 2^* - 1$, and $2^* = \frac{2N}{N-2}$. For any initial data in the energy space $H_0^1(\Omega)$, there exists some finite time $T > 0$ and a local in time solution w belonging to $C([0, T]; H_0^1(\Omega))$ (this is a consequence of the $L^p + 1$ -existence result in [3] for any $1 < p \leq 2^* - 1$ and of the smoothing effect of the heat kernel). In this framework, the energy functional is given by

$$I_p(u) := \frac{1}{2} \|\nabla u\|_{L^2}^2 - \frac{1}{p+1} \|u\|_{L^{p+1}}^{p+1}.$$

Let $u \in H_0^1(\Omega) \setminus \{0\}$, and let us analyze the energy of the function σu for any $\sigma \geq 0$. By an easy computation, one can show that

$$I_p(\sigma u) := \frac{\sigma^2}{2} \|\nabla u\|_{L^2}^2 - \frac{\sigma^{p+1}}{p+1} \|u\|_{L^{p+1}}^{p+1}.$$

attains its unique maximum at a point $\bar{\sigma} = \bar{\sigma}(u) > 0$, and $\bar{u} := \bar{\sigma} u$ satisfies $\|\nabla \bar{u}\|_{L^2}^2 - \|\bar{u}\|_{L^{p+1}}^{p+1} = 0$.

There, the energy $I(\sigma u)$ has the structure of a potential well, and every ray σu , for any $\sigma > 0$ and for $u \in H_0^1(\Omega) \setminus \{0\}$, has a unique intersection with the *Nehari manifold*

$$N = \left\{ u \in H_0^1(\Omega) \setminus \{0\} : \|\nabla u\|_{L^2}^2 - \|u\|_{L^{p+1}}^{p+1} = 0 \right\}.$$

The depth of the well is given by the lowest pass over the ridge define by all possible maps $\sigma \mapsto I_p(\sigma u)$ as u ranges over $H_0^1(\Omega) \setminus \{0\}$, namely

$$d_p := \inf_{u \in H_0^1(\Omega) \setminus \{0\}} \max_{\sigma \geq 0} I_p(\sigma u).$$

It is well known that d_p can be characterized as

$$d_p = \inf_{u \in N} I_p(u), \quad \text{and also } d_p = \frac{p-1}{2(p+1)} \Lambda^{\frac{2(p+1)}{p-1}},$$

where $\Lambda = \Lambda_{p+1}(\Omega)$ is the best constant in the Sobolev embedding $H_0^1(\Omega) \subset L^{p+1}(\Omega)$, i.e.,

$$\Lambda = \inf_{u \in H_0^1(\Omega) \setminus \{0\}} \frac{\|\nabla u\|_{L^2}}{\|u\|_{L^{p+1}}}.$$

If $1 < p < 2^* - 1$, then d_p is the energy level of ground state solutions.

The potential well associated with the Cauchy problem (2) is the set

$$W_p := \left\{ u \in H_0^1(\Omega) : I_p(u) < d_p, \|\nabla u\|_{L^2}^2 - \|u\|_{L^{p+1}}^{p+1} > 0 \right\} \cup \{0\},$$

and the exterior of the potential well is

$$V_p := \left\{ u \in H_0^1(\Omega) : I_p(u) < d_p, \|\nabla u\|_{L^2}^2 - \|u\|_{L^{p+1}}^{p+1} < 0 \right\}.$$

The sets V_p and W_p are both invariant under the flow associated with (2). Concerning the stable set, if $1 < p < 2^* - 1$, any solution which enters the stable set W_p exists globally in time. This result is a direct consequence of the fact that, in the subcritical case, the time T of local existence of the solution to (2) depends only on the size of the norm of the initial data in $H_0^1(\Omega)$, and for any $u \in W_p$ the Dirichlet norm $\|\nabla u\|_{L^2}$ is uniformly bounded (see[4]).

Definition 1 We say that (u, v) is a semitrivial solution of (1) if (u, v) satisfies (1) and $u \not\equiv 0, v \equiv 0$ or $u \equiv 0, v \not\equiv 0$. On the other hand, (u, v) is called a (nontrivial) vector solution if (u, v) is a solution of (1) with $u \not\equiv 0, v \not\equiv 0$. A pair (u, v) is called positive if $u > 0, v > 0$ in Ω .

The stationary problem. For $i = 1, 2$, consider the following single equation

$$-\Delta u + \lambda_i u = \mu_i u \left(e^{u^2} - 1 \right) \text{ in } \Omega, u \in H_0^1(\Omega), \tag{3}$$

whose corresponding functional is given by $J_{\lambda_i, \mu_i} : H_0^1(\Omega) \rightarrow \mathbb{R}$,

$$J_{\lambda_i, \mu_i}(u) = \frac{1}{2} \int_{\Omega} \left(|\nabla u|^2 + \lambda_i u^2 \right) dx - \frac{\mu_i}{2} \int_{\Omega} \left(e^{u^2} - 1 - u^2 \right) dx.$$

Notice that if u_1, u_2 solve the single equation (3) for $i = 1, 2$ respectively, then $(u_1, 0)$ and $(0, u_2)$ solve system (1).

By [5, Theorem 1.3], problem (3) admits a mountain pass solution u_{λ_i, μ_i} with minimal energy $E_i < 2\pi$, where

$$E_i = \inf \left\{ J_{\lambda_i, \mu_i}(u) : u \in H_0^1(\Omega) \setminus \{0\}, J'_{\lambda_i, \mu_i}(u) = 0 \right\}, \tag{4}$$

namely a ground state solution.

Set

$$\beta_1 := \mu_1 \frac{\int_{\Omega} u_1^2 \left(e^{u_1^2} - 1 \right) dx}{\int_{\Omega} u_1^4 dx} \text{ and } \beta_2 := \mu_2 \frac{\int_{\Omega} u_2^2 \left(e^{u_2^2} - 1 \right) dx}{\int_{\Omega} u_2^4 dx}.$$

It is not difficult to show that the stationary problem associated with (1), i.e.,

$$\begin{cases} -\Delta u + \lambda_1 u = \mu_1 u \left(e^{u^2} - 1 \right) + \beta v \left(e^{uv} - 1 \right) & \text{in } \Omega, \\ -\Delta v + \lambda_2 v = \mu_2 v \left(e^{v^2} - 1 \right) + \beta u \left(e^{uv} - 1 \right) & \text{in } \Omega, \\ u, v \in H_0^1(\Omega) \end{cases} \tag{5}$$

Therefore, from now on, we will assume $\lambda_1, \lambda_2 > -\Lambda_1$ and $\beta > \bar{\beta}_0$ where

$$\bar{\beta}_0 = 4 \frac{\max \{E_1 \beta_1, E_2 \beta_2\}}{\min \{E_1, E_2\}} > 0.$$

The existence of ground state solutions for (5) is proved in [6]. From [6, Lemma 4.2], we also know that the mountain pass level

$$d_{\beta}^{MP} := \inf_{\gamma \in \Gamma} \max_{t \in [0, 1]} I(\gamma(t)), \quad \Gamma := \{ \gamma \in C([0, 1], X) : \gamma(0) = 0, I(\gamma(1)) < 0 \}. \tag{6}$$

Moreover,

$$0 < d_{\beta}^{MP} < 2\pi. \tag{7}$$

Another useful characterization of the mountain pass level c can be obtained by means of the Nehari functional

$$J(u, v) := \langle dI(u, v), (u, v) \rangle = \int_{\Omega} \left(\lambda_1 u^2 + |\nabla u|^2 + \lambda_2 v^2 + |\nabla v|^2 \right) dx - \int_{\Omega} [uH_u(u, v) + vH_v(u, v)] dx. \tag{8}$$

Let

$$d_\beta := \inf \{I(u, v) : (u, v) \in X \setminus \{(0, 0)\}, J(u, v) = 0\},$$

where $X = H_0^1(\Omega) \times H_0^1(\Omega)$, then the existence of a mountain pass solution $(u_\beta, v_\beta) \in X \setminus \{(0, 0)\}$ to (5) implies $I(u_\beta, v_\beta) = d_\beta^{MP}$ and $dI(u_\beta, v_\beta) \equiv 0$; therefore, $d_\beta \leq I(u_\beta, v_\beta) = d_\beta^{MP}$. And in [6] we also know that $d_\beta^{MP} \leq d_\beta$; hence,

$$d_\beta = d_\beta^{MP}, \tag{9}$$

and this can be deduced from the geometry of J and I in the energy space. In particular, (9) is a consequence of the following property which gives also the potential well structure of the energy functional I .

Proposition 1 For any $(u, v) \in X \setminus \{(0, 0)\}$, there exists a unique $\bar{\sigma} = \bar{\sigma}(u, v) > 0$ such that

$$J(\sigma u, \sigma v) = \begin{cases} > 0 & \text{if } 0 < \sigma < \bar{\sigma}, \\ = 0 & \text{if } \sigma = \bar{\sigma}, \\ < 0 & \text{if } \sigma > \bar{\sigma}. \end{cases} \tag{10}$$

We will proof Proposition 1 in Section 2 by simple computations.

Stable and unstable set. According to Proposition 1, for any fixed $(u, v) \in X \setminus \{(0, 0)\}$, the function $\sigma \mapsto I(\sigma u, \sigma v)$ has the shape of a potential well. The idea of the potential well approach is to constrain the solution to (1) in the well to the left of $\bar{\sigma}(u, v)$ to ensure global existence. To ensure that the solution of (1) is constrained, we must find the lowest passage of the ridge defined by all possible $I(\sigma u, \sigma v)$ as (u, v) ranges over $X \setminus \{(0, 0)\}$. The height of the lower pass over the ridge is the mountain pass level \tilde{c} and $\tilde{c} = d_\beta$

Therefore, the potential well argument suggests to consider the splitting of the d -sublevel set of the energy I determined by the Nehari functional J . More precisely, we consider the unstable set V and the stable set W defined, respectively, by

$$V := \{(u, v) \in X \setminus \{(0, 0)\} : I(u, v) < d_\beta, J(u, v) < 0\},$$

and

$$W := \{(u, v) \in X \setminus \{(0, 0)\} : I(u, v) < d_\beta, J(u, v) > 0\} \cup \{0\}.$$

Theorem 2 Let $(u, v) \in C([0, T_*]; X \setminus \{(0, 0)\})$ be the maximal solution to (1), and $(u_0, v_0) \in X \setminus \{(0, 0)\}$. If $(u(t_0), v(t_0)) \in V$ for some $t_0 \in [0, T_*)$, then $T_* < +\infty$.

2 Preliminaries

Let $\Omega \subset \mathbb{R}^2$ be any smooth domain, and let us consider the more general Cauchy problem

$$\begin{cases} \partial_t u = \Delta u + g_1(u, v) & \text{in } \Omega \times (0, T), \\ \partial_t v = \Delta v + g_2(u, v) & \text{in } \Omega \times (0, T), \\ u(x, t) = v(x, t) = 0 & \text{on } \partial\Omega \times (0, T), \\ u(x, 0) = u_0(x), v(x, 0) = v_0(x) & \text{in } \Omega, \end{cases} \tag{11}$$

where $(u_0, v_0) \in X \setminus \{(0, 0)\}$, and $g_i \in C^1(\mathbb{R}, \mathbb{R})$ satisfies

(g1) $g(0) = 0$, and

(g2) for any $\varepsilon > 0$ we have

$$|g(s_1) - g(s_2)| \leq C_\varepsilon |s_1 - s_2| \left(e^{(1+\varepsilon)s_1^2} + e^{(1+\varepsilon)s_2^2} \right), \quad s_1, s_2 \in \mathbb{R}.$$

for some positive constant C_ε .

Definition 2 Let $(u_0, v_0) \in X \setminus \{(0, 0)\}$. We say that (u, v) is a solution to (11) if $(u, v) \in C([0, T]; X \setminus \{(0, 0)\})$, and (u, v) verifies the integral equation

$$\begin{pmatrix} u(t) \\ v(t) \end{pmatrix} = \begin{pmatrix} e^{t\Delta} u_0 + \int_0^t e^{(t-s)\Delta} g_1(u(s), v(s)) ds \\ e^{t\Delta} v_0 + \int_0^t e^{(t-s)\Delta} g_2(u(s), v(s)) ds \end{pmatrix}.$$

Theorem 3 ([5]). If $\alpha \in (0, 4\pi)$, then there exists a constant $C_\alpha > 0$ such that

$$\int_{\mathbb{R}^2} (e^{\alpha v^2} - 1) dx \leq C_\alpha \|v\|_{L^2}^2, \text{ for any } v \in H^1(\mathbb{R}^2) \text{ with } \|\nabla v\|_{L^2} \leq 1, \tag{12}$$

and the above inequality fails if $\alpha \geq 4\pi$.

Theorem 4 Let $0 < m < 4\pi$, and $M > 0$. There exists $T = T(m, M) > 0$ such that, for any $(u_0, v_0) \in X \setminus \{(0, 0)\}$ with

$$\|\nabla(u_0, v_0)\|_{L^2}^2 \leq m \text{ and } \|(u_0, v_0)\|_{L^2}^2 \leq M, \tag{13}$$

the Cauchy problem (1) has a unique solution $(u, v) \in C([0, T]; X \setminus \{(0, 0)\})$.

Proof. In order to prove the existence of a unique solution $(u, v) \in C([0, T]; X \setminus \{(0, 0)\})$, let us first write the equation in (1) in the equivalent integral formulation

$$\begin{pmatrix} u(t) \\ v(t) \end{pmatrix} = \begin{pmatrix} e^{t\Delta}u_0 + \int_0^t e^{(t-s)\Delta} \left(-\lambda_1 u + \mu_1 u (e^{u^2} - 1) + \beta v (e^{uv} - 1) \right) ds \\ e^{t\Delta}v_0 + \int_0^t e^{(t-s)\Delta} \left(-\lambda_2 v + \mu_2 v (e^{v^2} - 1) + \beta u (e^{uv} - 1) \right) ds \end{pmatrix}. \tag{14}$$

Since $0 < m < 4\pi$ there exists $\varepsilon \in (0, 1)$ such that $m = 4\pi(1 - \varepsilon)$. Let us consider the set

$$\begin{aligned} X &= X(m, M) \\ &= \left\{ (u, v) \in L^\infty((0, T), X \setminus \{(0, 0)\}) : \sup_{t \in [0, T]} \|\nabla(u(t), v(t))\|_{L^2}^2 \leq 4\pi \left(1 - \frac{\varepsilon}{2}\right); \sup_{t \in [0, T]} \|(u, v)\|_{L^2}^2 \leq 2M \right\}. \end{aligned}$$

This set endowed with the distance

$$\begin{aligned} d((u_1, v_1), (u_2, v_2)) &= \sup_{t \in [0, 1]} \|\nabla(u_1(t), v_1(t)) - \nabla(u_2(t), v_2(t))\|_{L^2} \\ &\quad + \sup_{t \in [0, 1]} \|(u_1(t), v_1(t)) - (u_2(t), v_2(t))\|_{L^2} \end{aligned}$$

is a complete metric space. We show that if $T > 0$ is small enough the map

$$\Phi(u, v) = \begin{pmatrix} \Phi_1 u \\ \Phi_2 v \end{pmatrix} = \begin{pmatrix} e^{t\Delta}u_0 + \int_0^t e^{(t-s)\Delta} \left(-\lambda_1 u + \mu_1 u (e^{u^2} - 1) + \beta v (e^{uv} - 1) \right) ds \\ e^{t\Delta}v_0 + \int_0^t e^{(t-s)\Delta} \left(-\lambda_2 v + \mu_2 v (e^{v^2} - 1) + \beta u (e^{uv} - 1) \right) ds \end{pmatrix}$$

is a contraction form X into itself. We remark that (u_0, v_0) satisfies

$$\|\nabla(u_0, v_0)\|_{L^2} \leq \sqrt{m} = \sqrt{4\pi(1 - \varepsilon)} < \sqrt{4\pi \left(1 - \frac{\varepsilon}{2}\right)}, \quad \|(u_0, v_0)\|_{L^2} \leq \sqrt{M}.$$

Let us first prove that Φ maps X into itself.

$$\begin{aligned} \|\Phi_1(u, v)(t)\|_{L^2} &\leq \|e^{t\Delta}(u_0, v_0)\|_{L^2} + \int_0^t \left\| e^{(t-s)\Delta} \left(-\lambda_1 u + \mu_1 u (e^{u^2} - 1) + \beta v (e^{uv} - 1) \right) \right\|_{L^2} ds \\ &\leq \|(u_0, v_0)\|_{L^2} + \int_0^t \left\| e^{(t-s)\Delta} \left(-\lambda_1 u + \mu_1 u (e^{u^2} - 1) + \beta v (e^{uv} - 1) \right) \right\|_{L^2} ds \\ &\leq \|(u_0, v_0)\|_{L^2} + \int_0^t \left\| e^{(t-s)\Delta} \left(-\lambda_1 u + \mu_1 u (e^{u^2} - 1) \right) \right\|_{L^2} ds + \int_0^t \left\| e^{(t-s)\Delta} \beta v (e^{uv} - 1) \right\|_{L^2} ds \end{aligned}$$

we have

$$\int_0^t \left\| e^{(t-s)\Delta} \beta v (e^{uv} - 1) \right\|_{L^2} ds \leq C\beta \int_0^t \frac{1}{(t-s)^{\frac{1}{r}-\frac{1}{s}}} \|v(s)(e^{uv} - 1)\|_{L^r} ds$$

where $1 < r < 2$ will be chosen later. By holder inequality we have

$$\begin{aligned}
\|v(s)(e^{uv} - 1)\|_r^r &= \int_{\Omega} |v(s)(e^{uv} - 1)|^r dx \\
&\leq \int_{\Omega} |v(s)|^r (e^{r uv} - 1) dx \\
&\leq \left(\int_{\Omega} |v(s)|^{rp} dx \right)^{\frac{1}{p}} \left(\int_{\Omega} (e^{rquv} - 1) dx \right)^{\frac{1}{q}} \\
&\leq C \|u\|_2^r \left(\int_{\Omega} (e^{rquv} - 1) dx \right)^{\frac{1}{q}} \\
&\leq C (\|u\|_2^2 + \|v\|_2^2)^{\frac{r}{2}} \left(\int_{\Omega} (e^{rquv} - 1) dx \right)^{\frac{1}{q}} \\
&\leq C \|(u, v)\|_{H^1}^r \left(\int_{\Omega} (e^{rquv} - 1) dx \right)^{\frac{1}{q}} \\
&\leq M
\end{aligned}$$

where $rp \geq 2$, and p, q will be chosen later. By [6, Lemma 2.1 and Lemma 2.3] and young inequality we have

$$\begin{aligned}
\int_{\Omega} (e^{rquv} - 1) dx &= \int_{\Omega} \left(e^{\sqrt{rqu} \cdot \sqrt{rqu}} - 1 \right)^{2 \cdot \frac{1}{2}} dx \\
&\leq \int_{\Omega} \left[(e^{rqu^2} - 1) (e^{rquv^2} - 1) \right]^{\frac{1}{2}} dx \\
&\leq \int_{\Omega} \left(e^{2rqu^2} + e^{rquv^2} \right)^{\frac{1}{2}} dx \\
&< +\infty
\end{aligned}$$

Now choosing $q = 1 + \varepsilon^2, r = 1 + \varepsilon^4$, we can estimate

$$\int_0^t \left\| e^{(t-s)\Delta} \beta v (e^{uv} - 1) \right\|_{L^2} ds \leq C(\beta, M, \varepsilon) \int_0^t \frac{1}{(t-s)^{\frac{1}{r}-\frac{1}{2}}} ds = \tilde{C} t^{\frac{3}{2}-\frac{1}{r}}.$$

Now, we estimate $\int_0^t \left\| e^{(t-s)\Delta} (-\lambda_1 u + \mu_1 u (e^{u^2} - 1)) \right\|_{L^2} ds$. We set $\bar{g}(u) = -\lambda_1 u + \mu_1 u (e^{u^2} - 1)$ and by [7] \bar{g} satisfy (g2), so we have

$$\begin{aligned}
\int_0^t \left\| e^{(t-s)\Delta} \bar{g}(u(s)) \right\|_{L^2} ds &\leq C \int_0^t \left\| e^{(t-s)\Delta} |u(s)| \left(e^{(1+\varepsilon)u^2(s)} + 1 \right) \right\|_{L^2} ds \\
&\leq 2C \int_0^t \left\| e^{(t-s)\Delta} |u(s)| \right\|_{L^2} ds + C \int_0^t \left\| e^{(t-s)\Delta} |u(s)| \left(e^{(1+\varepsilon)u^2(s)} - 1 \right) \right\|_{L^2} ds \\
&\leq 2Ct\sqrt{2M} + C \int_0^t \frac{1}{(t-s)^{\frac{1}{r}-\frac{1}{2}}} \left\| |u(s)| \left(e^{(1+\varepsilon)u^2(s)} - 1 \right) \right\|_{L^r} ds
\end{aligned}$$

The values of r and q are the same above. Since we have

$$\begin{aligned}
\left\| |u(s)| \left(e^{(1+\varepsilon)u^2(s)} - 1 \right) \right\|_{L^r}^r &\leq \int_{\Omega} |u(s)|^r \left(e^{r(1+\varepsilon)u^2(s)} - 1 \right) dx \\
&\leq \left(\int_{\Omega} |u(s)|^{rp} dx \right)^{\frac{1}{p}} \left(\int_{\Omega} \left(e^{rq(1+\varepsilon)u^2(s)} - 1 \right) dx \right)^{\frac{1}{q}} \\
&\leq C \|(u, v)\|_{H^1}^r \left(\int_{\Omega} \left(e^{rq(1+\varepsilon)u^2(s)} - 1 \right) dx \right)^{\frac{1}{q}}
\end{aligned}$$

by Moser-Trudinger inequality and $m < 4\pi \left(1 - \frac{\varepsilon}{2}\right)$ we have

$$\begin{aligned} \left(\int_{\Omega} \left(e^{rq(1+\varepsilon)u^2(s)} - 1\right) dx\right)^{\frac{1}{q}} &= \left(\int_{\Omega} \left(e^{(1+\varepsilon)^2(1+\varepsilon)^4(1+\varepsilon)m\left(\frac{u(s)}{\sqrt{m}}\right)^2} - 1\right) dx\right)^{\frac{1}{q}} \\ &= \left(\int_{\Omega} \left(e^{4\pi(1-\varepsilon)s\left(\frac{u(s)}{\sqrt{m}}\right)^2} - 1\right) dx\right)^{\frac{1}{q}} \\ &\leq \left(\frac{1}{m} \|u(s)\|_{L^2}^2\right)^{\frac{1}{q}} \\ &\leq C \frac{\|(u, v)\|_{L^2}^2}{m} \\ &\leq C \left(\frac{2M}{m}\right)^{\frac{1}{q}} \end{aligned}$$

Therefore, if T is sufficiently small depending only on m, M then

$$\|\Phi_1(u, v)(t)\|_{L^2} \leq \sqrt{2M}.$$

Next for any $(u, v) \in X$ and for any $t \in [0, T]$, thanks to $\|v(s)(e^{uv} - 1)\|_{L^r}^r \leq C$, we obtain

$$\begin{aligned} \|\nabla(\Phi_1(u, v)(t))\|_{L^2} &\leq \|e^{t\Delta}\nabla(u_0, v_0)\|_{L^2} + \int_0^t \left\| \nabla e^{(t-s)\Delta} \left(-\lambda_1 u + \mu_1 u (e^{u^2} - 1) + \beta v (e^{uv} - 1)\right) \right\|_{L^2} ds \\ &\leq \|e^{t\Delta}\nabla(u_0, v_0)\|_{L^2} + \int_0^t \left\| \nabla e^{(t-s)\Delta} \left(-\lambda_1 u + \mu_1 u (e^{u^2} - 1)\right) \right\|_{L^2} ds \\ &\quad + \int_0^t \left\| \nabla e^{(t-s)\Delta} \beta v (e^{uv} - 1) \right\|_{L^2} ds \\ &\leq \sqrt{m} + C_{\varepsilon} \int_0^t \frac{1}{\sqrt{t-s}} \left\| \sqrt{t-s} \nabla e^{(t-s)\Delta} \left[|u(s)| (e^{(1+\varepsilon)u^2} + 1)\right] \right\|_{L^2} ds \\ &\quad + C\beta \int_0^t \frac{1}{(t-s)^{\frac{1}{r}}} \|v(s)(e^{uv} - 1)\|_{L^2} ds \end{aligned}$$

since

$$\begin{aligned} &C_{\varepsilon} \int_0^t \frac{1}{\sqrt{t-s}} \left\| \sqrt{t-s} \nabla e^{(t-s)\Delta} \left[|u(s)| (e^{(1+\varepsilon)u^2} + 1)\right] \right\|_{L^2} ds \\ &\leq 2C_{\varepsilon} \int_0^t \frac{1}{\sqrt{t-s}} \left\| \sqrt{t-s} \nabla e^{(t-s)\Delta} \left[|u(s)| (e^{(1+\varepsilon)u^2} + 1)\right] \right\|_{L^2} ds \\ &\quad + C_{\varepsilon} \int_0^t \frac{1}{\sqrt{t-s}} \left\| \sqrt{t-s} \nabla e^{(t-s)\Delta} \left[|u(s)| (e^{(1+\varepsilon)u^2} - 1)\right] \right\|_{L^2} ds \\ &\leq 2C_{\varepsilon} \sqrt{2Mt} + C_{\varepsilon, r} \int_0^t \frac{1}{(t-s)^{\frac{1}{r}}} \left\| |u(s)| (e^{(1+\varepsilon)u^2} - 1) \right\|_{L^r} ds \\ &\leq 2C_{\varepsilon} \sqrt{2Mt} + \tilde{C}_{\varepsilon, r} t^{1-\frac{1}{r}} \end{aligned}$$

with the same $1 < r < 2$ chosen above. There, if T is sufficiently small depending only on m, M then

$$\sup_{t \in [0, T]} \|\nabla(\Phi_1 u)(t)\|_{L^2} \leq \sqrt{4\pi \left(1 - \frac{\varepsilon}{2}\right)}.$$

In a similar way it is possible to prove that for $T = T(m, M)$ small enough the map Φ_1 is a contraction on X and also Φ_2 . Finally, by using the standard regularizing properties of the heat kernel it is possible to prove that the fixed point $u \in X$ of Φ satisfies $u \in C([0, T], H^1(\Omega))$. ■

3 Basic properties of the solution to the model problem (1)

Proposition 5 For any $t \in (0, T)$, we have

$$-\frac{d}{dt}I(u, v) = \|\partial_t u(t)\|_{L^2} + \|\partial_t v(t)\|_{L^2}, \quad (15)$$

$$\frac{1}{2} \frac{d}{dt} \left(\|u(t)\|_{L^2}^2 + \|v(t)\|_{L^2}^2 \right) = -\|(u(t), v(t))\|_{H^1}^2 + \int_{\Omega} [uH_u(u, v) + vH_v(u, v)] dx \quad (16)$$

and

$$|\langle dI(u, v), (\varphi, \psi) \rangle| \leq \|\partial_t u(t)\|_{L^2} \|\varphi\|_{L^2} + \|\partial_t v(t)\|_{L^2} \|\psi\|_{L^2}, \text{ for any } \varphi, \psi \in H^1(\Omega) \quad (17)$$

Proof. The monotonicity of the energy (15) follows by Green formula and direct calculation $\frac{d}{dt}I(u, v)$. And (16) follows by multiplying the equation in (1) by (u, v) and integrating over Ω . Finally, to deduce (17) we multiply the equation in (1) by $(\varphi, \psi) \in H^1(\Omega) \times H^1(\Omega)$, and we integrate over Ω , obtaining (17). ■

We complete this section with the following continuity result that can be proved arguing as in [7, Proposition 3.6] with minor modifications.

Lemma 6 If $T > 0$ and $(u, v) \in C([0, T], H^1(\Omega)) \times C([0, T], H^1(\Omega))$, then

$$J(u, v) \in C([0, T], \mathbb{R}) \times C([0, T], \mathbb{R}).$$

4 Blow-up in V

If $(u, v) \in V$, and $\bar{\sigma} = \bar{\sigma}(u, v) > 0$ is given by Proposition 1, then $\bar{\sigma} \in (0, 1)$, and hence,

$$2d_{\beta} \leq 2I(\bar{\sigma}u, \bar{\sigma}v) \leq \|(\bar{\sigma}u, \bar{\sigma}v)\|_{H^1}^2 < \|(u, v)\|_{H^1}^2. \quad (18)$$

To prove the invariance of the set V under the flow associated with (1), it is crucial to recall that, from (7) and (9), we know that

$$d_{\beta} > 0. \quad (19)$$

Lemma 7 Let $(u, v) \in C((0, T_*]; H^1(\mathbb{R})) \times C((0, T_*]; H^1(\mathbb{R}))$ be the maximal solution to (1), and $(u_0, v_0) \in X$. If $(u(t_0), v(t_0)) \in V$ for some $t_0 \in [0, T_*)$, then $(u, v) \in V$ for any $t \in [t_0, T_*)$.

Proof. In view of the monotonicity of the energy (15), and by Lemma 6, it is enough to prove that $J(u(t), v(t)) \neq 0$ for any $t \in (t_0, T_*)$. If $J(u(t), v(t)) = 0$ for some $t \in (t_0, T_*)$, then there exists $t_1 \in (t_0, T_*)$ such that

$$J(u(t), v(t)) < 0 \text{ for any } t \in [t_0, t_1), \text{ and } J(u(t_1), v(t_1)) = 0.$$

Therefore, $(u(t), v(t)) \in V$ for any $t \in [t_0, t_1)$, and

- either $(u(t_1), v(t_1)) \neq 0$. Hence $d_{\beta} \leq I(u(t_1), v(t_1))$, which is not possible due to the monotonicity of the energy (15)
- or $(u(t_1), v(t_1)) = 0$ which yields

$$\lim_{t \rightarrow t_1^-} \|u(t), v(t)\|_{H^1} = \|u(t_1), v(t_1)\|_{H^1} = 0,$$

and this contradicts (18) and (19).

■

In order to prove that solutions entering V blow up in finite time, we will apply the following blow-up Lemma containing the classical idea of the concavity method due to Levine [8].

Lemma 8 ([8]). *There exists no non-negative and increasing function $y \in C^2(\bar{t}, +\infty)$, with $\bar{t} \in \mathbb{R}$, such that, for some $\gamma > 0$,*

$$y(t)y''(t) \geq (\gamma + 1)[y'(t)]^2 \text{ on } (\bar{t}, +\infty),$$

and

$$\lim_{t \rightarrow +\infty} y(t) = +\infty. \tag{20}$$

Proof. We can prove Lemma 8 by applying the arguments in [2, lemma 4.2] or [8]. In view of (20), $h(t) := y^{-\gamma}(t)$ is well defined on the half-line $(t', +\infty)$, for some $t' \geq \bar{t}$ sufficiently large. Moreover,

$$\lim_{t \rightarrow +\infty} h(t) = 0. \tag{21}$$

■
The concavity method works in our setting due to the fact the Nehari functional along solutions entering V is bounded away from zero by a strictly negative constant.

Proposition 9 *Let $(u, v) \in C([0, T_*]; H^1(\Omega)) \times C([0, T_*]; H^1(\Omega))$ be the maximal solution to (1) with $\beta > \bar{\beta}_0$, and $(u_0, v_0) \in X$. If $(u(t_0), v(t_0)) \in V$ for some $t_0 \in [0, T_*)$ then there exists $\varepsilon > 0$ such that $J(u(t), v(t)) < -\varepsilon$ for any $t \in [t_0, T_*)$.*

Proof. Let

$$d'_\beta := \inf \{K(u, v) : (u, v) \in H^1(\Omega) \times H^1(\Omega) \setminus \{(0, 0)\}, J(u, v) \leq 0\},$$

where

$$K(u, v) := I(u, v) - \frac{1}{2}J(u, v) = \int_\Omega \frac{1}{2} [uH_u(u, v) + vH_v(u, v)] - H(u, v) dx \tag{22}$$

Then, $d_\beta = d'_\beta$. In fact, clearly $d'_\beta \leq d_\beta$, and in order to deduce that $d_\beta \leq d'_\beta$, it is enough to show that

$$d_\beta \leq K(u, v) \text{ for any } (u, v) \in H^1(\Omega) \times H^1(\Omega) \setminus \{(0, 0)\} \text{ with } J(u, v) < 0.$$

Let $(u, v) \in H^1(\Omega) \times H^1(\Omega) \setminus \{(0, 0)\}$, and let $\bar{\sigma} = \bar{\sigma}(u, v) > 0$ be as in Proposition 1. If $J(u, v) < 0$, then $\bar{\sigma}(u, v) \in (0, 1)$, and by [2, Proposition 4.3] with a minor modifications we can get

$$d_\beta \leq I(\bar{\sigma}u, \bar{\sigma}v) = K(u, v).$$

With the above characterization of d_β , it is easy to show that for any $\varepsilon > 0$

$$d_{\beta\varepsilon} := \inf \{I(u, v) : (u, v) \in H^1(\Omega) \times H^1(\Omega) \setminus \{(0, 0)\}, J(u, v) = -\varepsilon\} \geq d - \frac{\varepsilon}{2} \tag{23}$$

In fact, by direct computations

$$\begin{aligned} d_{\beta\varepsilon} &= \inf \left\{ I(u, v) + \frac{\varepsilon}{2} - \frac{\varepsilon}{2} : (u, v) \in H^1(\Omega) \times H^1(\Omega) \setminus \{(0, 0)\}, J(u, v) = -\varepsilon \right\} \\ &= \inf \left\{ I(u, v) - \frac{1}{2}J(u, v) - \frac{\varepsilon}{2} : (u, v) \in H^1(\Omega) \times H^1(\Omega) \setminus \{(0, 0)\}, J(u, v) = -\varepsilon \right\} \\ &= \inf \left\{ I(u, v) - \frac{1}{2}J(u, v) : (u, v) \in H^1(\Omega) \times H^1(\Omega) \setminus \{(0, 0)\}, J(u, v) = -\varepsilon \right\} - \frac{\varepsilon}{2} \\ &= \inf \{K(u, v) : (u, v) \in H^1(\Omega) \times H^1(\Omega) \setminus \{(0, 0)\}, J(u, v) = -\varepsilon\} - \frac{\varepsilon}{2} \\ &\geq d_\beta - \frac{\varepsilon}{2}. \end{aligned}$$

Next, we assume that the maximal solution (u, v) to (1) satisfies $(u(t_0), v(t_0)) \in V$ for some $t_0 \in [0, T_*)$. Then, there exists $\varepsilon > 0$ such that

$$\min \{d_\beta - I(u(t_0), v(t_0)), -J(u(t_0), v(t_0))\} > \varepsilon$$

In view of (23) and the monotonicity of the energy (15), we get

$$d_{\beta\varepsilon} \geq d_\beta - \frac{\varepsilon}{2} > I(u(t_0), v(t_0)) \geq I(u(t), v(t)), \text{ for any } t \in [t_0, T_*). \tag{24}$$

Assume that $J(u(t_1), v(t_1)) = -\varepsilon$ for some $t_1 \in (t_0, T_*)$. Then, $d_{\beta\varepsilon} \leq I(u(t_1), v(t_1))$, which contradicts (24)

Summarizing, we have $J(u(t_0), v(t_0)) < -\varepsilon$, and $J(u(t), v(t)) \neq -\varepsilon$ for any $t \in [t_0, T_*)$. Therefore, the proof is complete in view of the continuity of J along the solution, see Lemma 6. ■

Proof of Theorem 2

Proof. We argue by contradiction assuming that the solution (u, v) is global, i.e., $T_* = \infty$, and we apply the blow-up Lemma 8 to the non-negative and increasing C^2 -function defined by

$$y(t) := \frac{1}{2} \int_{t_0}^t \|u(s)\|_{L^2}^2 + \|v(s)\|_{L^2}^2 ds, \quad t \in [t_0, +\infty). \tag{25}$$

In view of (16), we have

$$y''(t) = \frac{1}{2} \frac{d}{dt} (\|u(s)\|_{L^2}^2 + \|v(s)\|_{L^2}^2) = -J(u(t), v(t)) > \varepsilon, \quad t \in (t_0, +\infty), \tag{26}$$

where $\varepsilon > 0$ is given by Proposition 9. From (26), we deduce that

$$\lim_{t \rightarrow +\infty} y'(t) = \lim_{t \rightarrow +\infty} y(t) = +\infty. \tag{27}$$

Since there exists $\theta > 2$ such that

$$\theta H(a, b) \leq aH_a(a, b) + bH_b(a, b), \quad \text{for any } a, b \in \mathbb{R}$$

we can estimate

$$\begin{aligned} y''(t) &= -J(u(t), v(t)) \\ &= -\left(\lambda_1 \|u(t)\|_{L^2}^2 + \lambda_2 \|v(t)\|_{L^2}^2 + \|\nabla u(t)\|_{L^2}^2 + \|\nabla v(t)\|_{L^2}^2\right) + \int_{\Omega} [uH_u(u, v) + vH_v(u, v)] dx \\ &\geq -\left(\lambda_1 \|u(t)\|_{L^2}^2 + \lambda_2 \|v(t)\|_{L^2}^2 + \|\nabla u(t)\|_{L^2}^2 + \|\nabla v(t)\|_{L^2}^2\right) + \theta \int_{\Omega} H(u(t), v(t)) dx \\ &= -\theta I(u(t), v(t)) + (\theta - 1) \left(\lambda_1 \|u(t)\|_{L^2}^2 + \lambda_2 \|v(t)\|_{L^2}^2 + \|\nabla u(t)\|_{L^2}^2 + \|\nabla v(t)\|_{L^2}^2\right) \\ &= -\theta I(u(t), v(t)) + Cy'(t) \end{aligned}$$

where $C = C(\theta) := (\theta - 2) > 0$.

Using (15), we get

$$-I(u(t), v(t)) = \int_{t_0}^t \|\partial_s u(s)\|_{L^2}^2 + \|\partial_s v(s)\|_{L^2}^2 ds - I(u(t_0), v(t_0)), \tag{28}$$

and hence,

$$\begin{aligned} y(t) y''(t) &\geq \frac{\theta}{2} \left(\int_{t_0}^t \|u(s)\|_{L^2}^2 + \|v(s)\|_{L^2}^2 ds\right) \left(\int_{t_0}^t \|\partial_s u(s)\|_{L^2}^2 + \|\partial_s v(s)\|_{L^2}^2 ds\right) \\ &\quad + y(t) (Cy'(t) - \theta I(u(t_0), v(t_0))) \\ &\geq \frac{\theta}{2} \left(\int_{t_0}^t \left(\int_{\Omega} u(s) \partial_s u(s) dx\right) ds\right)^2 + y(t) (Cy'(t) - \theta I(u(t_0), v(t_0))) \\ &\geq \frac{\theta}{2} \left(\int_{t_0}^t \frac{1}{2} \frac{d}{ds} \|u(s)\|_{L^2}^2 ds\right)^2 + y(t) (Cy'(t) - \theta I(u(t_0), v(t_0))) \\ &= \frac{\theta}{2} (y'(t) - y'(t_0))^2 + y(t) (Cy'(t) - \theta I(u(t_0), v(t_0))). \end{aligned}$$

In view of (27), for any $\gamma \in (0, 1)$ there exists $t_\gamma > 1$ such that

$$y(t) y''(t) \geq \frac{\theta}{2} \gamma [y'(t)]^2, \quad \text{for any } t \geq t_\gamma.$$

If we choose $\gamma > 0$ such that $\frac{2}{\theta} < \beta < 1$, then we are in the framework of the blow-up Lemma 8, and we reach a contradiction. Thus we prove Theorem 2. ■

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