

Blow-up Profiles To a Nonlinear Degenerate Parabolic System with Nonlocal Boundary Condition

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Abstract: This paper deals with a nonlocal degenerate parabolic system with weighted nonlocal boundary condition. We give out the criteria for finite time blow-up or global existence, which shows the weight functions play the substantial roles in determining whether the solutions will blow-up or not.

Keywords: parabolic system; nonlocal boundary condition; global existence; blow up

1 Introduction

In this paper, we consider the following degenerate parabolic system

$$u_t = \Delta u^m + av^{p_1} \|v\|_\alpha^{p_2}, v_t = \Delta v^n + bu^{q_1} \|u\|_\beta^{q_2}, \quad x \in \Omega, t > 0, \quad (1.1)$$

with nonlocal boundary condition

$$u(x, t) = \int_\Omega f(x, y)u(y, t)dy, \quad v(x, t) = \int_\Omega g(x, y)v(y, t)dy, \quad x \in \partial\Omega, t > 0, \quad (1.2)$$

and initial data

$$u(x, 0) = u_0(x), v(x, 0) = v_0(x), \quad x \in \Omega, \quad (1.3)$$

where Ω is a bounded domain in $R^N (N \geq 1)$ with smooth boundary $\partial\Omega, m, n > 1, \alpha, \beta \geq 1, a, b > 0, p_i, q_i \geq 0, (i = 1, 2)$ and $(p_1 + p_2)(q_1 + q_2) > 0, \|\cdot\|_\alpha^\alpha = \int_\Omega |\cdot|^\alpha dx$. While $f(x, y), g(x, y)$ are nonnegative and continuous on $\partial\Omega \times \bar{\Omega}, u_0(x), v_0(x) \in C^{2+\theta}(\bar{\Omega})$ with $0 < \theta < 1, u_0(x), v_0(x) \geq 0$, and satisfy the compatibility conditions $u_0(x) = \int_\Omega f(x, y)u_0(y)dy, v_0(x) = \int_\Omega g(x, y)v_0(y)dy, x \in \partial\Omega$, respectively.

There have been many articles dealing with properties of solutions to degenerate parabolic equations or system with homogeneous Dirichlet boundary conditions (see [1, 5, 7, 9] and references therein). In [3, 4], Galaktionov et al. considered the system

$$u_t = \Delta u^{v+1} + v^p, \quad v_t = \Delta v^{\mu+1} + u^q, \quad x \in \Omega, t > 0, \quad (1.4)$$

subject to homogeneous Dirichlet boundary condition. They proved that every solution of (1.4) is global if $pq < (1 + v)(1 + \mu)$, and there are solutions blow up in finite time for sufficiently large initial data if $pq > (1 + v)(1 + \mu)$, which show that $p_c = pq - (1 + v)(1 + \mu)$ is the critical exponent of (1.4).

Furthermore, Deng et al. in [8] considered the system

$$u_t = \Delta u^m + \|v\|_\alpha^p, \quad v_t = \Delta v^n + \|u\|_\beta^q, \quad x \in \Omega, t > 0, \quad (1.5)$$

subject to homogeneous Dirichlet boundary condition. They proved the critical exponent is $p_c = pq - mn$.

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However, parabolic equations with nonlocal boundary conditions have been studied as well (see [10]-[13]). For example, Kong et al. in [10], by using some ideas of Souplet [7], obtained the blow-up conditions for the following system

$$u_t = \Delta u + u^m \int_{\Omega} v^n(x, t) dx, \quad v_t = \Delta v + v^q \int_{\Omega} u^p(x, t) dx, \quad x \in \partial\Omega, t > 0, \tag{1.6}$$

subject to nonlocal boundary (1.2). The typical characterization of (1.6) is the completely coupled of the nonlocal sources, which leads to the analysis of the simultaneous blow-up.

Motivated by [3],[4] and [8]-[10], we discuss how the weight functions in the boundary conditions affect the global and blow-up properties for problem (1.1)-(1.3). We will show that the weight functions $f(x, y), g(x, y)$ play substantial roles in determining blow-up or not of solutions.

This paper is organized as follows. In the next section, we give the comparison principle of the solution of problem (1.1)-(1.3). In Section 3, we will consider the global existence and blow-up of solution.

2 Comparison principle

Let $Q_T = \Omega \times (0, T), S_T = \partial\Omega \times (0, T)$ for $0 < T < \infty$. As it is now well known that degenerate equation need not possess classical solutions, we begin by giving a precise definition of a weak solution of (1.1)-(1.3).

Definition 2.1 A vector function $(w(x, t), z(x, t))$ defined on $\overline{Q_T}$, for some $T > 0$, is called a sub (or super) solution of problem (1.1)-(1.3) on $\overline{Q_T}$, if $w(x, t), z(x, t) \in C(\overline{Q_T}) \cap C^{2,1}(Q_T)$ and satisfy

$$\begin{aligned} w_t &\leq (\geq) \Delta w^m + az^{p_1} \|z\|_{\alpha}^{p_2}, & x \in \Omega, t > 0, \\ z_t &\leq (\geq) \Delta z^n + bw^{q_1} \|w\|_{\beta}^{q_2}, & x \in \Omega, t > 0, \\ (w(x, t), z(x, t)) &\leq (\geq) \left(\int_{\Omega} f(x, y)w(y, t)dy, \int_{\Omega} g(x, y)z(y, t)dy \right), & x \in \partial\Omega, t > 0, \\ (w(x, 0), z(x, 0)) &\leq (\geq) (u_0(x), v_0(x)), & x \in \Omega. \end{aligned} \tag{2.1}$$

A weak solution of problem (1.1)-(1.3) is a vector function which is both a subsolution and a supersolution of problem (1.1)-(1.3). Regarding the subsolution and the supersolution, we have the following comparison lemma which plays an important role in our proof.

Lemma 2.1 (Comparison principle). Let $(\underline{u}, \underline{v})$ and $(\overline{u}, \overline{v})$ be a nonnegative subsolution and a nonnegative supersolution of problem (1.1)-(1.3), respectively. Then $(\underline{u}, \underline{v}) \leq (\overline{u}, \overline{v})$ in $\overline{Q_T}$, if $(\underline{u}(x, 0), \underline{v}(x, 0)) \leq (\overline{u}(x, 0), \overline{v}(x, 0))$, and

$$\underline{u}, \underline{v} \geq \delta > 0 \quad \text{or} \quad \overline{u}, \overline{v} \geq \delta > 0. \tag{2.2}$$

Proof. Taking $\psi(x, t) \in \Psi \equiv \{\psi \in C(\overline{Q_T}); \psi_t, \Delta\psi \in C(Q_T) \cap L^2(Q_T); \psi \geq 0, \psi(x, t)|_{\partial\Omega \times (0, T)} = 0\}$ and multiplying the first and second inequalities in (2.1) by $\psi(x, t)$, then integrate them on $\Omega \times (0, t)$ for any $0 < t < T$, we obtain

$$\int_{\Omega} \underline{u}(x, t)\psi(x, t)dx \leq \int_{\Omega} \underline{u}(x, 0)\psi(x, 0)dx + \int_0^t \int_{\Omega} (\underline{u}\psi_{\tau} + \underline{u}^m \Delta\psi + a\underline{v}^{p_1} \|\underline{v}\|_{\alpha}^{p_2} \psi) dx d\tau - \int_0^t \int_{\partial\Omega} \frac{\partial \psi}{\partial \eta} \left(\int_{\Omega} f(x, y)\underline{u}(y, \tau) \right)^m dS d\tau, \tag{2.3}$$

$$\int_{\Omega} \underline{v}(x, t)\psi(x, t)dx \leq \int_{\Omega} \underline{v}(x, 0)\psi(x, 0)dx + \int_0^t \int_{\Omega} (\underline{v}\psi_{\tau} + \underline{v}^n \Delta\psi + b\underline{u}^{q_1} \|\underline{u}\|_{\beta}^{q_2} \psi) dx d\tau - \int_0^t \int_{\partial\Omega} \frac{\partial \psi}{\partial \eta} \left(\int_{\Omega} g(x, y)\underline{v}(y, \tau) \right)^n dS d\tau. \tag{2.4}$$

where η is the unit outward normal to the lateral boundary of Q_T . On the other hand, the supersolution $(\overline{u}, \overline{v})$ satisfies the reverse inequality

$$\int_{\Omega} \overline{u}(x, t)\psi(x, t)dx \geq \int_{\Omega} \overline{u}(x, 0)\psi(x, 0)dx + \int_0^t \int_{\Omega} (\overline{u}\psi_{\tau} + \overline{u}^m \Delta\psi + a\overline{v}^{p_1} \|\overline{v}\|_{\alpha}^{p_2} \psi) dx d\tau - \int_0^t \int_{\partial\Omega} \frac{\partial \psi}{\partial \eta} \left(\int_{\Omega} f(x, y)\overline{u}(y, \tau) \right)^m dS d\tau, \tag{2.5}$$

$$\int_{\Omega} \overline{v}(x, t)\psi(x, t)dx \geq \int_{\Omega} \overline{v}(x, 0)\psi(x, 0)dx + \int_0^t \int_{\Omega} (\overline{v}\psi_{\tau} + \overline{v}^n \Delta\psi + b\overline{u}^{q_1} \|\overline{u}\|_{\beta}^{q_2} \psi) dx d\tau - \int_0^t \int_{\partial\Omega} \frac{\partial \psi}{\partial \eta} \left(\int_{\Omega} g(x, y)\overline{v}(y, \tau) \right)^n dS d\tau. \tag{2.6}$$

By (2.3) and (2.5), we have

$$\begin{aligned} & \int_{\Omega} [\underline{u}(x, t) - \bar{u}(x, t)] \psi(x, t) dx \\ & \leq \int_{\Omega} [\underline{u}(x, 0) - \bar{u}(x, 0)] \psi(x, 0) dx + \int_0^t \int_{\Omega} [\psi_{\tau} + E_1(x, \tau) \Delta \psi] (\underline{u} - \bar{u}) dx d\tau \\ & \quad + \int_0^t \int_{\Omega} (a \|\underline{v}\|_{\alpha}^{p_2} \psi E_2(x, \tau) (\underline{v} - \bar{v}) + a \bar{v}^{p_1} \psi E_4(\tau) \int_{\Omega} E_3(x, \tau) (\underline{v} - \bar{v}) dx) dx d\tau \\ & \quad - \int_0^t \int_{\partial\Omega} \frac{\partial \psi}{\partial \eta} m \xi^{m-1} (\int_{\Omega} f(x, y) (\underline{u}(y, \tau) - \bar{u}(y, \tau)) dy) dS d\tau, \end{aligned}$$

where

$$\begin{aligned} E_1(x, \tau) &= \int_0^1 m(\theta \underline{u} + (1 - \theta) \bar{u})^{m-1} d\theta, & E_2(x, \tau) &= \int_0^1 p_1(\theta \underline{v} + (1 - \theta) \bar{v})^{p_1-1} d\theta, \\ E_3(x, \tau) &= \int_0^1 \alpha(\theta \underline{v} + (1 - \theta) \bar{v})^{\alpha-1} d\theta, & E_4(\tau) &= \int_0^1 \frac{p_2}{\alpha} (\theta \|\underline{v}\|_{\alpha}^{p_2} + (1 - \theta) \|\bar{v}\|_{\alpha}^{p_2})^{\frac{p_2}{\alpha}-1} d\theta, \\ \xi & \text{ is a function between } \int_{\Omega} f(x, y) \underline{u}(y, t) dy \text{ and } \int_{\Omega} f(x, y) \bar{u}(y, t) dy. \end{aligned}$$

Since $(\underline{u}, \underline{v})$ and (\bar{u}, \bar{v}) are bounded Q_T , it follows from $m > 1, \alpha \geq 1$ that $E_1(x, \tau), E_3(x, \tau)$ are bounded nonnegative functions. Similarly, $E_2(x, \tau), E_4(\tau)$ are bounded if $p_1, \frac{p_2}{\alpha} \geq 1$. Now, if $p_1, \frac{p_2}{\alpha} < 1$, we have $E_2(x, \tau) \leq \delta^{p_1-1}, E_4(\tau) \leq (\delta^{p_2} |\Omega|^{\frac{p_2}{\alpha}})^{\frac{p_2}{\alpha}-1}$, by the assumptions (2.2). In addition, $\partial \psi / \partial \eta \leq 0$ on $\partial \Omega$. Thus, we can choose the appropriate test function ψ as in [2, p.118-123] to obtain

$$\begin{aligned} & \int_{\Omega} [\underline{u}(x, t) - \bar{u}(x, t)]_+ dx \\ & \leq C_1 \int_{\Omega} [\underline{u}(x, 0) - \bar{u}(x, 0)]_+ dx + C_2 \int_0^t \int_{\Omega} [\underline{v} - \bar{v}]_+ dx d\tau \\ & \leq C_2 \int_0^t \int_{\Omega} [\underline{v} - \bar{v}]_+ dx d\tau. \end{aligned} \tag{2.7}$$

where $w_+ \equiv \max\{w, 0\}$ and using $\underline{u}(x, 0) - \bar{u}(x, 0) \leq 0$. Similarly, we can prove

$$\int_{\Omega} [\underline{v}(x, t) - \bar{v}(x, t)]_+ dx \leq C_3 \int_0^t \int_{\Omega} [\underline{u} - \bar{u}]_+ dx d\tau. \tag{2.8}$$

Now, (2.7),(2.8) combined with the Gronwall's lemma show that $(\underline{u}, \underline{v}) \leq (\bar{u}, \bar{v})$, Thus, this proof is completed. ■

Local in time existence of positive classical solutions of problem (1.1)-(1.3) can be obtained by using fixed point theorem (see [6]), the representation formula and the contraction mapping principle as in [11]. By the above comparison principle, we get the uniqueness of solution to the problem. The proof is more or less standard, so is omitted here.

Remark 1 If $p_1 \geq 1, p_2 \geq 1, p_2 \geq \alpha, q_2 \geq \beta$, then the condition of (2.2) is not necessary in Lemma 2.1. In this case, it is also easy to see that the solution of problem (1.1)-(1.3) is unique.

3 Global existence and finite time blow-up

We use the upper and lower solutions method to deduce conditions on the global existence or blow-up in finite time for problem (1.1)-(1.3), and it can be observed that the weight functions $f(x, y), g(x, y)$ play an important role in the discussions.

Theorem 3.1 Suppose that $\int_{\Omega} f(x, y) dy \geq 1, \int_{\Omega} g(x, y) dy \geq 1$ for any $x \in \partial \Omega$. If $(p_1 + p_2)(q_1 + q_2) > 1$, then any solution of problem (1.1)-(1.3) with positive initial data blows up in finite time.

Proof. Let $(F(t), H(t))$ be the unique solution of the following ordinary differential equations

$$\begin{aligned} F'(t) &= a |\Omega|^{\frac{p_2}{\alpha}} H^{p_1+p_2}(t), & H'(t) &= b |\Omega|^{\frac{q_2}{\beta}} F^{q_1+q_2}(t), & t > 0, \\ F(0) &= \frac{1}{2} \min_{\bar{\Omega}} u_0(x) > 0, & H(0) &= \frac{1}{2} \min_{\bar{\Omega}} v_0(x) > 0, \end{aligned} \tag{3.1}$$

Under the condition $(p_1 + p_2)(q_1 + q_2) > 1$, we know that $(F(t), H(t))$ blows up in the finite time T^* . Set $\underline{u}(x, t) = F(t), \underline{v}(x, t) = H(t)$, then we obtain

$$\begin{aligned} \underline{u}_t &= \Delta \underline{u}^m + a \underline{v}^{p_1} \|\underline{v}\|_{\alpha}^{p_2}, & \underline{v}_t &= \Delta \underline{v}^n + b \underline{u}^{q_1} \|\underline{u}\|_{\beta}^{q_2}, & x \in \Omega, t > 0, \\ \underline{u}(x, t) &\leq \int_{\Omega} f(x, y) \underline{u}(y, t) dy, & \underline{v}(x, t) &\leq \int_{\Omega} g(x, y) \underline{v}(y, t) dy, & x \in \partial \Omega, t > 0, \\ \underline{u}(x, 0) &\leq u_0(x), & \underline{v}(x, 0) &\leq v_0(x), & x \in \Omega, \end{aligned} \tag{3.2}$$

By Lemma 2.1, we get $(\underline{u}(x, t), \underline{v}(x, t)) \leq (u(x, t), v(x, t))$. So $(u(x, t), v(x, t))$ blows up in a finite time for any positive initial data. ■

Theorem 3.2 Suppose that $\int_{\Omega} f(x, y)dy < 1, \int_{\Omega} g(x, y)dy < 1$ for any $x \in \partial\Omega$.

(1) If $[(p_1 + p_2)(q_1 + q_2) < mn$, then every nonnegative solution of problem (1.1)-(1.3) is global;

(2) If $(p_1 + p_2)(q_1 + q_2) = mn$, then every nonnegative solution of problem (1.1)-(1.3) is global provided that a and b are sufficiently small;

(3) If $(p_1 + p_2)(q_1 + q_2) > mn$, then the nonnegative solution of problem (1.1)-(1.3) exists globally for sufficiently small initial data and blows up in finite time for sufficiently large initial data.

Proof. Let $\varphi_1(x), \varphi_2(x)$ be the positive solution of the following linear elliptic problem, respectively

$$-\Delta\varphi_1(x) = \varepsilon_1, \quad x \in \Omega, \quad \varphi_1(x) = \int_{\Omega} f(x, y)dy, \quad x \in \partial\Omega, \tag{3.3}$$

and

$$-\Delta\varphi_2(x) = \varepsilon_2, \quad x \in \Omega, \quad \varphi_2(x) = \int_{\Omega} g(x, y)dy, \quad x \in \partial\Omega, \tag{3.4}$$

where $\varepsilon_1, \varepsilon_2$ are positive constants such that $0 < \varphi_i(x) < 1$ ($i = 1, 2$) (since $\int_{\Omega} f(x, y)dy < 1, \int_{\Omega} g(x, y)dy < 1$, there exist such ε_i). Set $\overline{K}_1 = \max_{x \in \Omega} \varphi_1(x), \overline{K}_2 = \max_{x \in \Omega} \varphi_2(x)$. We define the functions \bar{u}, \bar{v} as following:

$$\bar{u}(x, t) = (M\varphi_1(x))^{l_1}, \quad \bar{v}(x, t) = (M\varphi_2(x))^{l_2}, \tag{3.5}$$

where $0 < l_1, l_2 < 1$ satisfy $ml_1, nl_2 < 1$ and M is a positive constant to be determined later. Then, we have for $x \in \Omega, t > 0$,

$$\begin{aligned} \bar{u}_t - \Delta\bar{u}^m - a\bar{v}^{p_1} \|\bar{v}\|_{\alpha}^{p_2} \\ = -ml_1(ml_1 - 1)\varphi_1^{ml_1-2} |\nabla\varphi_1|^2 M^{ml_1} + ml_1\varphi_1^{ml_1-1} M^{ml_1}\varepsilon_1 - a(M\varphi_2)^{p_1l_2} (\int_{\Omega} (M\varphi_2)^{\alpha l_2} dx)^{\frac{p_2}{\alpha}}, \\ \geq ml_1\overline{K}_1^{ml_1-1} M^{ml_1}\varepsilon_1 - a|\Omega|^{p_2/\alpha} (M\overline{K}_2)^{(p_1+p_2)l_2}, \end{aligned} \tag{3.6}$$

$$\bar{v}_t - \Delta\bar{v}^n - b\bar{u}^{q_1} \|\bar{u}\|_{\beta}^{q_2} \geq nl_2\overline{K}_2^{nl_2-1} M^{nl_2}\varepsilon_2 - b|\Omega|^{q_2/\beta} (M\overline{K}_1)^{(q_1+q_2)l_1}, \tag{3.7}$$

On the other hand, we have

$$\begin{aligned} \bar{u}(x, t)|_{\partial\Omega} = M^{l_1} (\int_{\Omega} f(x, y)dy)^{l_1} \geq M^{l_1} \int_{\Omega} f(x, y)dy \\ \geq M^{l_1} \int_{\Omega} f(x, y)\varphi_1^{l_1}(y)dy = \int_{\Omega} f(x, y)\bar{u}(y, t)dy, \end{aligned} \tag{3.8}$$

In a similar way, we have

$$\bar{v}(x, t)|_{\partial\Omega} \geq \int_{\Omega} g(x, y)\bar{v}(y, t)dy, \tag{3.9}$$

Here, we use the assumptions $0 < \varphi_1(x), \varphi_2(x) < 1$ and $\int_{\Omega} f(x, y)dy < 1, \int_{\Omega} g(x, y)dy < 1$. Denote

$$\begin{aligned} M_1 = \left(a(ml_1\varepsilon_1)^{-1} |\Omega|^{p_2/\alpha} \overline{K}_1^{1-ml_1} \overline{K}_2^{-(p_1+p_2)l_2} \right)^{1/(ml_1-(p_1+p_2)l_2)}, \\ M_2 = \left(b(nl_2\varepsilon_2)^{-1} |\Omega|^{q_2/\beta} \overline{K}_1^{-(q_1+q_2)l_1} \overline{K}_2^{1-nl_2} \right)^{1/(nl_2-(q_1+q_2)l_1)}. \end{aligned}$$

(1) If $(p_1 + p_2)(q_1 + q_2) < mn$, then there exist positive constants l_1, l_2 such that $(p_1 + p_2)/m < l_1/l_2 < n/(q_1 + q_2)$, and $ml_1, nl_2 < 1$. Hence

$$ml_1 > (p_1 + p_2)l_2, \quad nl_2 > (q_1 + q_2)l_1.$$

Thus, we can choose sufficiently large M such that $M > \max\{M_1, M_2\}$ and

$$(M\varphi_1(x))^{l_1} \geq u_0(x), \quad (M\varphi_2(x))^{l_2} \geq v_0(x). \tag{3.10}$$

From (3.6)-(3.10), we see that (\bar{u}, \bar{v}) is a positive supersolution of problem (1.1)-(1.3). Hence $(u, v) \leq (\bar{u}, \bar{v})$ by comparison principle, which implies (u, v) exists globally.

(2) If $(p_1 + p_2)(q_1 + q_2) = mn$, then there exist positive constants l_1, l_2 such that $ml_1 = (p_1 + p_2)l_2$, $nl_2 = (q_1 + q_2)l_1$ and $ml_1, nl_2 < 1$. According to (3.6)-(3.7), we can choose a, b to satisfy

$$a < ml_1\varepsilon_1|\Omega|^{-p_2/\alpha}\overline{K_1}^{-1}(\overline{K_1}/\overline{K_2})^{ml_1}, \quad b < nl_2\varepsilon_2|\Omega|^{-q_2/\beta}\overline{K_2}^{-1}(\overline{K_2}/\overline{K_1})^{nl_2}.$$

Then

$$\underline{u}_t - \Delta \underline{u}^m - a \underline{v}^{p_1} \|\underline{v}\|_\alpha^{p_2} \geq 0, \tag{3.11}$$

$$\underline{v}_t - \Delta \underline{v}^n - b \underline{u}^{q_1} \|\underline{u}\|_\beta^{q_2} \geq 0. \tag{3.12}$$

Furthermore, choose large enough M to satisfy (3.10). Then, it follows from (3.8)-(3.12) that $(\underline{u}, \underline{v})$ is a positive supersolution of problem (1.1)-(1.3). Therefore, (u, v) exists globally.

(3) If $(p_1 + p_2)(q_1 + q_2) > mn$, then there exist positive constants l_1, l_2 such that $ml_1, nl_2 < 1$ and

$$ml_1 < (p_1 + p_2)l_2, \quad nl_2 < (q_1 + q_2)l_1. \tag{3.13}$$

So, we can choose M sufficiently small such that $M < \min\{M_1, M_2\}$. Assume that $u_0(x)$ and $v_0(x)$ are sufficiently small to satisfy (3.10), and it follows that $(\underline{u}, \underline{v})$ defined by (3.5) is a positive supersolution of problem (1.1)-(1.3). Hence, (u, v) exists globally.

Next, we will prove the blow-up result. Let $\phi(x)$ be a nontrivial nonnegative continuous function, which vanishes on $\partial\Omega$. Without loss of generality, we may assume that $0 \in \Omega$ and $\phi(0) > 0$. Set

$$\underline{u}(x, t) = \frac{1}{(T-t)^{l_1}} \omega^{1/m} \left(\frac{|x|}{(T-t)^\sigma} \right), \quad \underline{v}(x, t) = \frac{1}{(T-t)^{l_2}} \omega^{1/n} \left(\frac{|x|}{(T-t)^\sigma} \right),$$

with

$$\omega(r) = \frac{R^3}{12} - \frac{R}{4}r^2 + \frac{1}{6}r^3, \quad r = \frac{|x|}{(T-t)^\sigma}, \quad 0 \leq r \leq R, \tag{3.14}$$

where $l_1, l_2, \sigma > 0$ and $0 < T < 1$ are constants to be chosen later. Clearly, $0 \leq \omega(r) \leq R^3/12$ and $\omega(r)$ is nonincreasing, since $\omega'(r) = r(r-R)/2 \leq 0$. We let T be small enough so that

$$\text{supp} \underline{u}(x, t) = \text{supp} \underline{v}(x, t) = \overline{B(0, R(T-t)^\sigma)} \subset \overline{B(0, RT^\sigma)} \subset \Omega. \tag{3.15}$$

Obviously, $(\underline{u}, \underline{v})$ becomes unbounded as $t \rightarrow T^-$, at the point $x = 0$. Calculating directly, we obtain that

$$\begin{aligned} & \underline{u}_t - \Delta \underline{u}^m - a \underline{v}^{p_1} \|\underline{v}\|_\alpha^{p_2} \\ &= \frac{ml_1\omega^{1/m}(r) + \sigma r \omega'(r) \omega^{(1-m)/m}}{m(T-t)^{l_1+1}} + \frac{NR - (N+1)r}{2(T-t)^{ml_1+2\sigma}} - \frac{a\omega^{p_1/n}(r)}{(T-t)^{l_2(p_1+p_2)}} \left(\int_{B(0, R(T-t)^\sigma)} |\omega(\frac{|x|}{(T-t)^\sigma})|^{\alpha/n} dx \right)^{p_2/\alpha}, \end{aligned}$$

$$\begin{aligned} & \underline{v}_t - \Delta \underline{v}^n - b \underline{u}^{q_1} \|\underline{u}\|_\beta^{q_2} \\ &= \frac{nl_2\omega^{1/n}(r) + \sigma r \omega'(r) \omega^{(1-n)/n}}{n(T-t)^{l_2+1}} + \frac{NR - (N+1)r}{2(T-t)^{nl_2+2\sigma}} - \frac{b\omega^{q_1/m}(r)}{(T-t)^{l_1(q_1+q_2)}} \left(\int_{B(0, R(T-t)^\sigma)} |\omega(\frac{|x|}{(T-t)^\sigma})|^{\beta/m} dx \right)^{q_2/\beta}, \end{aligned}$$

Case1. If $0 \leq r \leq NR/(N+1)$, we have $\omega(r) \geq R^3(3N+1)/12(N+1)^3$, then

$$\begin{aligned} & \underline{u}_t - \Delta \underline{u}^m - a \underline{v}^{p_1} \|\underline{v}\|_\alpha^{p_2} \\ & \leq \frac{l_1(R^3/12)^{1/m}}{(T-t)^{l_1+1}} + \frac{NR - (N+1)r}{2(T-t)^{ml_1+2\sigma}} - \frac{aM_1}{(T-t)^{l_2(p_1+p_2) - (N\sigma p_2/\alpha)}} \left(\frac{R^3(3N+1)}{12(N+1)^3} \right)^{p_1/n}, \end{aligned} \tag{3.16}$$

$$\begin{aligned} & \underline{v}_t - \Delta \underline{v}^n - b \underline{u}^{q_1} \|\underline{u}\|_\beta^{q_2} \\ & \leq \frac{l_2(R^3/12)^{1/n}}{(T-t)^{l_2+1}} + \frac{NR - (N+1)r}{(T-t)^{nl_2+2\sigma}} - \frac{bM_2}{(T-t)^{l_1(q_1+q_2) - (N\sigma q_2/\beta)}} \left(\frac{R^3(3N+1)}{12(N+1)^3} \right)^{q_1/m}, \end{aligned} \tag{3.17}$$

where $M_1 = \left(\int_{B(0, R)} \omega_+^{\alpha/n}(|\xi|) d\xi \right)^{p_2/\alpha}$, $M_2 = \left(\int_{B(0, R)} \omega_+^{\beta/m}(|\xi|) d\xi \right)^{q_2/\beta}$.

Case2. If $NR/(N+1) < r \leq R$, then

$$\underline{u}_t - \Delta \underline{u}^m - a \underline{v}^{p_1} \|\underline{v}\|_\alpha^{p_2} \leq \frac{l_1(R^3/12)^{1/m}}{(T-t)^{l_1+1}} - \frac{(N+1)r - NR}{2(T-t)^{ml_1+2\sigma}}, \tag{3.18}$$

$$v_t - \Delta v^n - b\underline{u}^{q_1} \|\underline{u}\|_\beta^{q_2} \leq \frac{l_2(R^3/12)^{1/n}}{(T-t)^{l_2+1}} - \frac{(N+1)r - NR}{(T-t)^{nl_2+2\sigma}}. \quad (3.19)$$

When l_1, l_2 are large enough to satisfy (3.13) and $l_1(m-1) > 1$, $l_2(n-1) > 1$, we can choose positive constant σ be sufficiently small such that

$$\sigma < \min\left\{\frac{l_2(p_1 + p_2) - ml_1}{2 + (Np_2/\alpha)}, \frac{l_1(q_1 + q_2) - nl_2}{2 + (Nq_2/\beta)}\right\},$$

Thus, we have

$$l_2(p_1 + p_2) - (N\sigma p_2/\alpha) > ml_1 + 2\sigma > l_1 + 1, \quad l_1(q_1 + q_2) - (N\sigma q_2/\beta) > nl_2 + 2\sigma > l_2 + 1.$$

Hence, for sufficiently small $T > 0$, (3.16)-(3.19) imply that

$$\underline{u}_t - \Delta \underline{u}^m - a\underline{v}^{p_1} \|\underline{v}\|_\alpha^{p_2} \leq 0, \quad \underline{v}_t - \Delta \underline{v}^n - b\underline{u}^{q_1} \|\underline{u}\|_\beta^{q_2} \leq 0, \quad (x, t) \in Q_T.$$

Since $\phi(0) > 0$ and $\phi(x)$ is continuous, there exist two positive constants ρ and ε such that $\phi(x) \geq \varepsilon$, for all $x \in B(0, \rho) \subset \Omega$. Choose T small enough to ensure $B(0, RT^\sigma) \subset B(0, \rho)$, hence $\underline{u} \leq 0, \underline{v} \leq 0$ on S_T . Under the assumption that $\int_\Omega f(x, y)dy < 1, \int_\Omega g(x, y)dy < 1$ for any $x \in \partial\Omega$, we have $\underline{u}(x, t) \leq \int_\Omega f(x, y)\underline{u}(y, t)dy, \underline{v}(x, t) \leq \int_\Omega g(x, y)\underline{v}(y, t)dy$ on S_T . Furthermore, choose $u_0(x), v_0(x)$ so large that $u_0(x) \geq \underline{u}(x, 0), v_0(x) \geq \underline{v}(x, 0)$. By comparison principle, we have $(\underline{u}, \underline{v}) \leq (u, v)$. It shows that solution (u, v) blows up in finite time. ■

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